

ABSTRACT

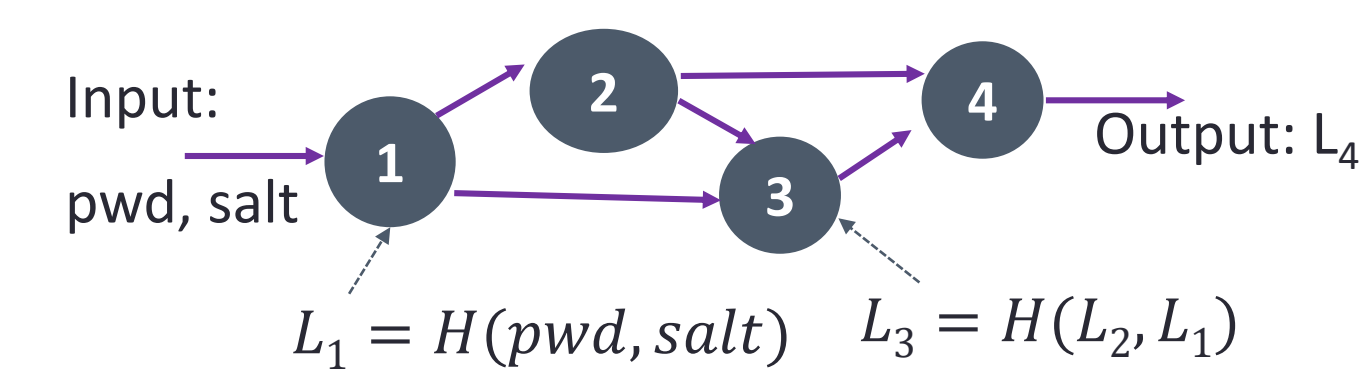
We demonstrate an algorithm for evaluating data-independent memory-hard functions (iMHFs) with significantly less cumulative resources (e.g., memory/energy) than ideally desired of such algorithms. In particular we get that:

- Catena-Dragonfly and Catena-Butterfly can be computed by an algorithm with cumulative cost $O(n^{5/3})$ --- an improvement of $O(n^{1/3})$.
- Argon2i (winner of the Password Hashing Competition) can be computed by an algorithm with cumulative cost $\tilde{O}(n^{7/4})$ --- an improvement of $\tilde{O}(n^{1/4})$.
- Any iMHF can be computed by algorithm with cumulative cost $O\left(\frac{n^2}{\log^{1-\epsilon} n}\right)$ for any constant $\epsilon > 0$ --- an improvement of $O(\log^{1-\epsilon} n)$.

In particular, this shows that the goal of constructing an iMHF requiring $\Omega(n^2)$ cumulative resources is infeasible.

iMHF (Password Hash Function)

- A data-independent memory hard function (iMHF) is defined by
- an underlying compression function H , and
 - a directed-acyclic graph (DAG) representing data-dependencies



Advantage: Data-dependent MHFs (e.g., SCRYPT) are vulnerable to side-channel attacks due to their data-dependent memory access pattern.

Computing an iMHF (Pebbling)

Pebbling Rules:

- May place a pebble on node v_1 during any round.
- May remove a pebble from DAG in any round.
- May place a pebble on an unpebbled node v_i during round j only if all parents had pebbles on round $j-1$.

Pebbling Costs:

- (Each Round) pay energy cost (1 mwt) for each pebble --- cost to store value in memory.
- Pay energy cost \bar{R} to place a new pebble on the DAG (e.g., $\bar{R} \approx 3,000$ mwt is cost to compute H)

Cumulative Cost of Pebbling Algorithm A:

$$cc(A) = \bar{R} \times (\#queries(H)) + \sum_{j=1}^{\#rounds} (\#pebbles(j))$$

Naïve Pebbling Algorithm N:

- Pebble graph in topological order (n rounds).
- Cumulative Cost:

$$cc(N) = O(n^2)$$

Attack Quality and Ideal iMHFs

(Amortized) Quality of Attack A

$$Quality(A) = \frac{CC(Naive)}{CC(A) \times \#inst(A)}$$

Amortized by #instances of iMHF computed.

c-Ideal iMHF

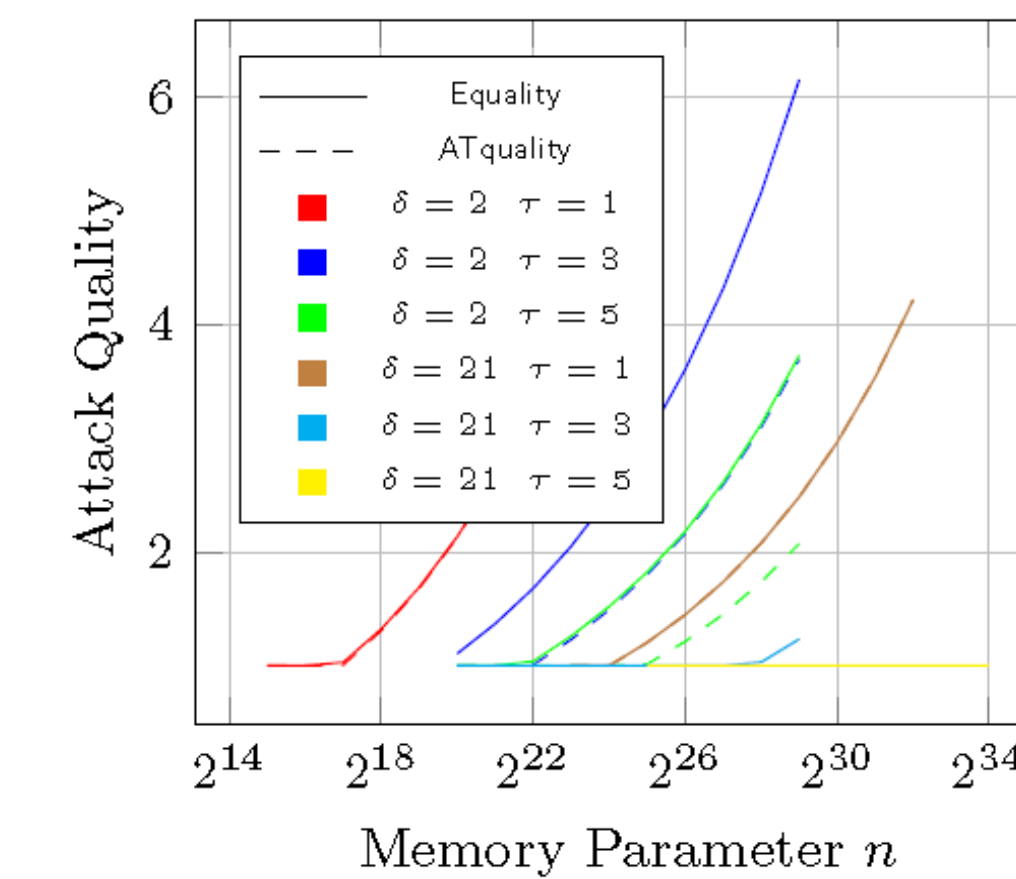
- For all attacks A , $Quality(A) \leq c$
- DAG has constant indegree

Thm (Bad News): No c-Ideal iMHF exists for $c = O(\log^{1-\epsilon} n)$.

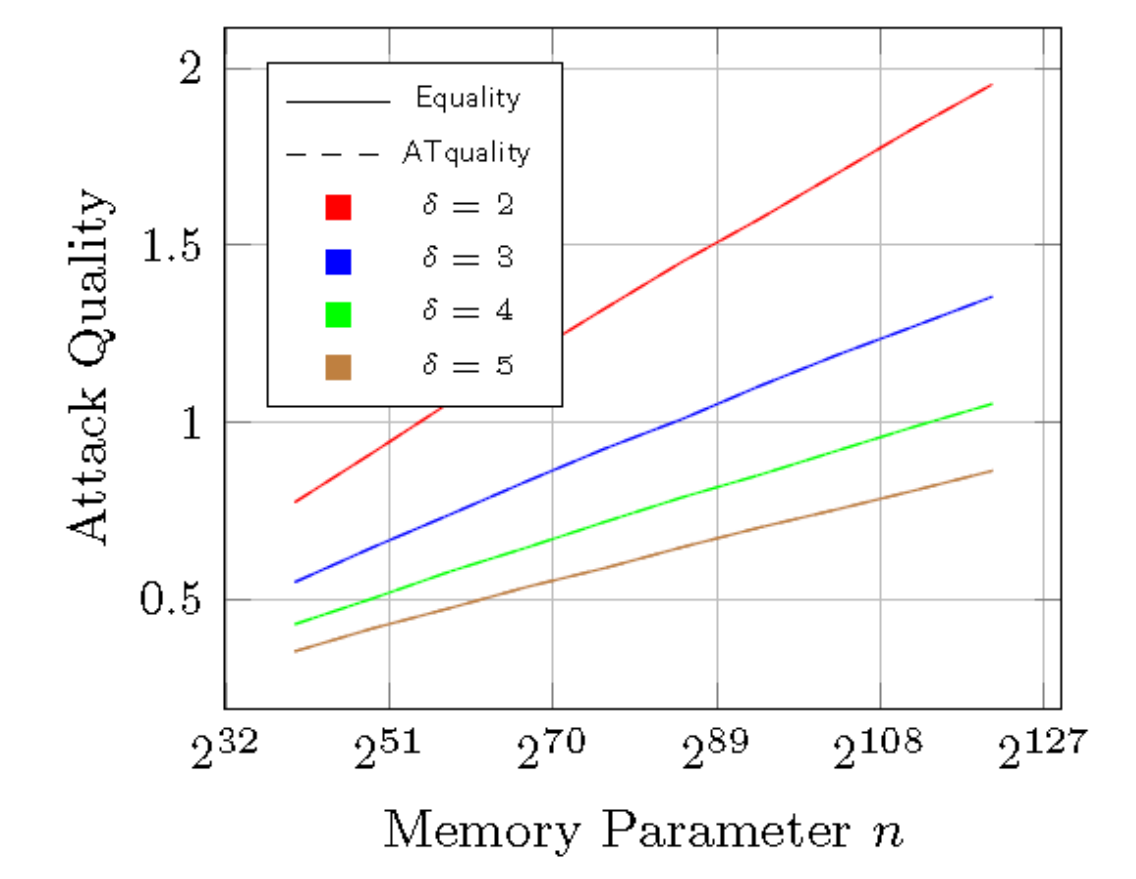
Significance?

- Cost of computing H varies greatly across architectures.
- Contrast:** memory costs are consistent across architectures.

PRACTICAL RESULTS



(a) Argon2i and SB



(b) Ideal iMHF

Depth-Robust DAGs are Necessary

Definition: We say that a DAG $G=(V,E)$ is (e,d) -node robust if

$$\forall S \subseteq V: |S| \leq e \Rightarrow \text{depth}(G - S) \geq d.$$

Length of longest remaining path after removing nodes in S .

Theorem (Depth-Robustness is a necessary condition): If G is not (e,d) -node robust then is an (efficient) attack A such that

$$Quality(A) = \Omega\left(\max_{d \leq g \leq n} \left\{ \frac{gn}{dn+g^2+ge} \right\}\right).$$

Theorem (No DAG is sufficiently depth robust): If a DAG $G=(V,E)$ has constant indegree then we can (efficiently) find $S \subseteq V$, s.t

$$|S| \leq O(n / \log^{1-\epsilon} n) \text{ and } \text{depth}(G - S) \leq n / \log^2 n$$

Note: yields attack with $Quality(A) = \Omega(\log^{1-\epsilon} n)$.

MAIN ATTACK (GEN-PEBBLE)

Algorithm 1: GenPeb (G, S, g, d)

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Arguments:  $G = (V, E)$ ,  $S \subseteq V$ ,  $g \in [\text{depth}(G - S), n]$ ,  $d \geq \text{depth}(G - S)$ 
1 for  $i = 1$  to  $n$  do
2   Pebble node  $i$ .
3    $l \leftarrow \lfloor i/g \rfloor * g + d + 1$ 
4   if  $i \bmod g \in [d]$  then // Balloon Phase
5      $d' \leftarrow d - (i \bmod g) + 1$ 
6      $N \leftarrow \text{need}(l, i + g, d')$ 
7     Pebble every  $v \in N$  which has all parents pebbled.
8     Remove pebble from any  $v \notin K$  where  $K \leftarrow S \cup \text{keep}(i, i + g) \cup \{n\}$ .
9   else // Light Phase
10     $K \leftarrow S \cup \text{parents}(i, i + g) \cup \{n\}$ 
11    Remove pebbles from all  $v \notin K$ .
12  end
13 end

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In $\leq d$ rounds we can recover all of the pebbles.

One Balloon Phase:
Cost = $O(dn)$

All Balloon Phases:
Total Cost = $O(dn^2/g)$.

Each round of a balloon phase is potentially very expensive.

Key: balloon phase ends quickly!

Light Phase: Discard most pebbles!

- Only keep pebbles on parents of next g nodes.
- One Light Phase: Cost = $O(g|S|)$
- All Light Phases: Total Cost = $O(g|S|(n/g)) = O(n|S|)$

Attacking Argon2i

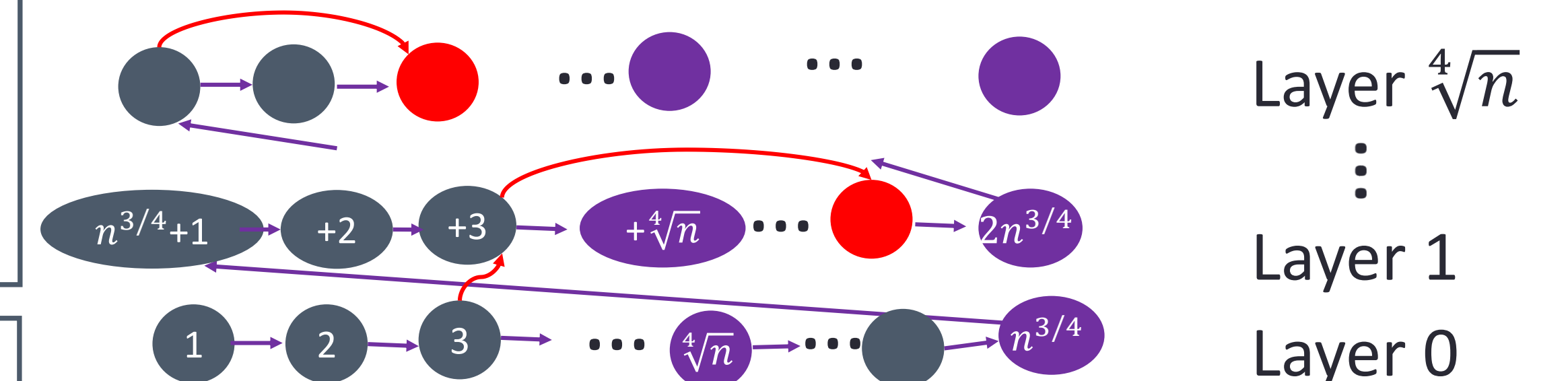
Argon2i DAG: $G=(V,E)$, indegree=2

Edges: (v_i, v_{i+1}) , $(v_{r(i)}, v_i)$ for $i \leq n$ $r(i) \sim \text{Uniform}([i-1])$

Lemma: Let $S_1 = \{v_i | i = j \times \sqrt[4]{n}\}$, and

$S_2 = \{v_i | v_{r(i)} \text{ and } v_i \text{ in same layer}\}$. Then

$\text{depth}(G - S_1 - S_2) \leq \sqrt{n}$, and $E[S_2] = O(n^{3/4} \log n)$



CONCLUSION

Practical attacks against every (known) iMHFs:

- Argon2i
- Catena
- Balloon Hashing (New)

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